# Considerations for Landing <br> Accuracy and Landed Mass 

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## Approaches to Accessing High-Risk Terrain

- Precision landing (< $10 \mathrm{~km}, 3$-sigma)
- Target safe landing region within mobility range of landed asset
- Pinpoint landing (10s of meters, 3-sigma)
- Allows landing in close proximity to desired surface feature
- Target small "safe zone" within larger unit of hazardous terrain
- Shotgun approach
- Multiple small penetrators blanket target feature
- Reliance on statistics of large numbers to provide success probability



## Landing Footpring Improvement Through Precision Landing Technology



| $300$ | Pathfinder, Mars 98 |
| :---: | :---: |
| 100 | Improved approach |
| 50 | navigation |
| 10 | <Autonomous aeromaneuvering L/D < 0.3 |
| Dispersion size, km | -Autonomous aeromaneuvering L/D > 0.8 |
|  | $R$ Autonomous terrain matching |
| . 1 |  |
| . 01 | Obstacle avoidance |
|  | Courtesy Bobby Braun, |

## Strategies to Improve Landed Accuracy



## U.S. Mars Mission EDL Summary (Successful and Planned Missions)

| Mission | Viking | MPF | MER | Phoenix | MSL |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Entry from | Orbit | Direct | Direct | Direct | Direct |
| Inertial entry velocity, km/s | 4.7 | 7.3 | 5.5 | 5.6 | $<6.0$ |
| Inertial entry flight path angle, deg | -17 | -14.1 | -11.5 | -13 | -15.2 |
| Ballistic coefficient, $\mathrm{kg} / \mathrm{m2}$ | 64 | 63 | 94 | 65 | 115 |
| Entry mass, kg | 992 | 584 | 830 | 600 | 2920 |
| Hypersonic guidance | Unguided | Unguided | Unguided | Unguided | Guided |
| Lift-to-drag ratio | 0.18 | 0.18 | 0 | 0 | 0.24 |
| Parachute deploy altitude, km | 5.8 | 9.4 | 7.4 | 9.8 | 6.5 |
| Touchdown rock height capability, cm | 20 | 50 | 50 | 30 | 100 |
| Touchdown slope capability, deg | 15 | $>30$ | $>30$ | 16 | $>15$ |
| Touchdown mass, kg | 590 | 360 | 539 | 350 | 800 |
| Landing ellipse major axis, km | 280 | 200 | 80 | 100 | 20 |
| Landing ellipse minor axis, km | 100 | 100 | 12 | 21 | 20 |
| Landing site elevation, km MOLA | -3.5 | -2.5 | -1.4 | -4 | 2 |

Adapted from Braun \& Manning, "Mars Exploration Entry, Descent and Landing Challenges"

## Approximate Limits on Landed Mass Using Current Technologies

## Assumptions

- MER packaging density within aeroshell assumed to be an upper limit
- 70 deg sphere-cone aeroshell configuration
- 6 km/s entry velocity
- Atmospheric opacity ~ 0.3
- 19.7 m parachute deployed at Mach 2.1
- Need 15 s timeline from Mach 0.8 to altitude of 1 km (start of propulsive descent)
- Lift-up L/D of 0.18 to maximize parachute deployment altitude

| MOLA Surface <br> Elevation $(\mathrm{km})$ | Maximum Ballistic <br> Coefficient (kg/m2) | Maximum Landed Mass <br> for 2.65 m Diameter <br> Aeroshell | Maximum Landed <br> Mass for 4.5 m <br> Diameter Aeroshell |
| :---: | :---: | :---: | :---: |
| -2 | 160 | 350 | 1000 |
| 0 | 135 | 300 | 850 |
| 2 | 115 | 250 | 750 |

Credit: Braun \& Manning, "Mars Exploration Entry, Descent and Landing Challenges"

